

# Chapter 1: Introduction

## Fundamental idea:

Under the future based on current state of conditions.

Def. A **system** is a set of measurable quantities, and a **dynamical system** is a system changing in time.

We use **models** to analyze.

Def. The **state** of a system is a set of values describing the system at time.

- The state space: all poss. states
- The time evolution rule: the function that describes how the system changes over time.

Two kinds of systems.

Def. A **discrete time dynamical system** is a dynamical system with discrete time steps: example  $t_0, t_1, t_2, \dots$

Def. A **continuous time dynamical system** is a dyn. sys. that changes continuously with time.

Continuous DS: differential eq.

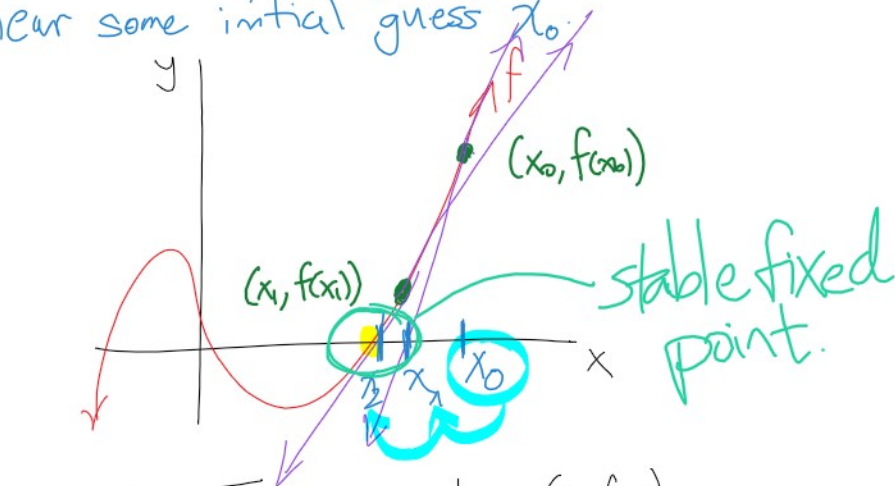
Discrete DS: difference eq.

1.1: Newton-Raphson Method.

## 1.1: Newton-Raphson Method

Method to find zeros/roots of functions  $f: \mathbb{R} \rightarrow \mathbb{R}$ .

Suppose  $f$  is diff. function, and we want a root ( $\bar{x} \in \mathbb{R}, f(\bar{x}) = 0$ ) near some initial guess  $x_0$ .



Start with  $x_n$ , we have  $(x_n, f(x_n))$   
Want tangent line of  $f$  thru  $\nearrow$   
Call this  $T_n(x) = mX + c$ .

$$m = f'(x_n) \quad f(x_n) = m x_n + c$$

$$c = f(x_n) - f'(x_n) x_n$$

$$T_n(x) = f'(x_n)(x - x_n) + f(x_n)$$

The intersection is  $0 = T_n(x)$ .

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

This yields a discrete D.S.

initial guess is  $x_0$

the next is  $x_1, x_2, \dots$

## 1.2: Exponential Growth/Decay.

Discrete.  $a \in \mathbb{R}^+$  ( $a > 0$ ),

$x_0 \in \mathbb{R}$ , for all  $n \in \mathbb{N}$ ,

$$x_{n+1} = a \cdot x_n$$

difference  
equation  $\rightarrow$

diff. eq.

$$x_{n+1} - x_n = a x_n - x_n$$

$$x_{n+1} = a \cdot x_n$$

difference equation

$$x_{n+1} - x_n = ax_n - x_n = (a-1)x_n = \lambda x_n$$

$$x_1 = a \cdot x_0$$

$$x_2 = a x_1 = a(a x_0) = a^2 x_0$$

$$x_3 = a \cdot x_2 = a^3 x_0$$

$$x_n = a^n x_0$$

Want to understand long term behavior.

Case 1:  $a=1$ .  $x_n = x_0$

Case 2:  $a > 1$ .

•  $x_0 = 0$ . System always 0.

This is a **fixed point**.

•  $x_0 > 0$ .  $x_{n+1} > x_n$ .

$$x_0 < x_1 < x_2 < \dots$$

$(x_n)_{n=0}^{\infty}$  is monotonically increasing.  $\rightarrow \infty$

•  $x_0 < 0$ .  $x_{n+1} < x_n < 0$

$$x_0 > x_1 > x_2 > \dots$$

$(x_n)_{n=0}^{\infty}$  is mon. dec.  $\rightarrow -\infty$

Going away from  $x=0$

$x=0$  is unstable fixed point

Case 3:  $0 < a < 1$ .

•  $x_0 = 0$ . Then system is fixed at  $x=0$ , so  $x=0$  is a fp.

•  $x_0 > 0$ .  $x_{n+1} < x_n$

$$x_0 > x_1 > x_2 > \dots (x_n) \rightarrow 0$$

mon. dec. all pos.  $x_n > 0$

•  $x_0 < 0$ .  $x_{n+1} > x_n$ .

$$x_0 < x_1 < x_2 < \dots (x_n) \rightarrow 0$$

mon. inc. all neg.  $x_n < 0$

Going towards  $x=0$ .

$x=0$  is a stable fixed point

Cont. 1.  $\begin{matrix} \cdot \\ \times \\ \parallel \end{matrix}$

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Cont.  $\frac{dx}{dt} = x' = \lambda x$

$x$  depends only on  $t$ , and this D.E describes how  $x$  changes.